



LCM-4TC

User manual



Website: <http://www.we-con.com.cn/en>

Technical Support: support@we-con.com.cn

Skype: fcwkkj

Phone: 86-591-87868869

QQ: 1043098682

Technical forum: <http://wecon.freeforums.net/>



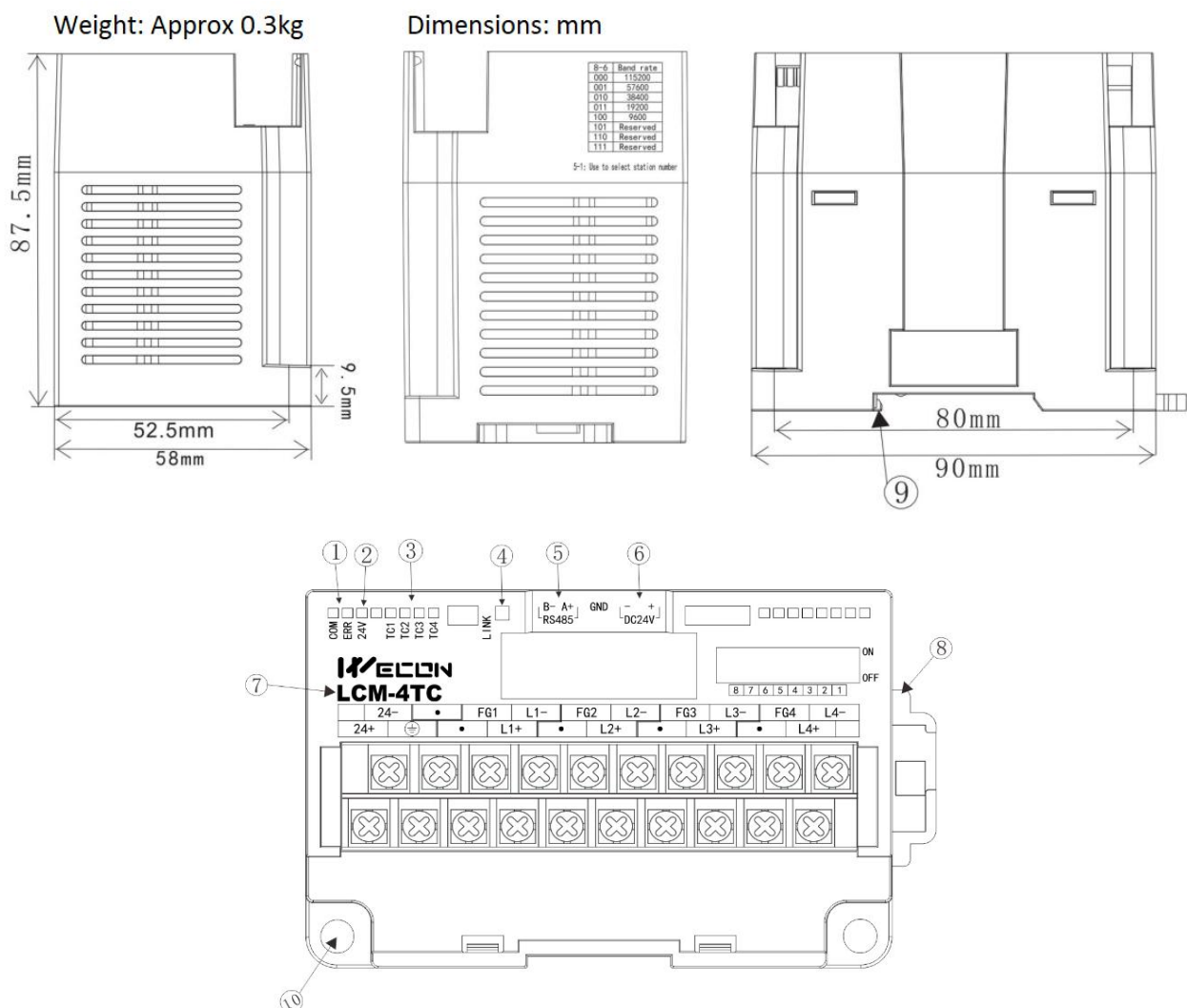
1. Introduction

LCM-4TC expansion module amplifies the signal from four thermocouple sensors (Type K or J) and converts the data into 12 bit value stored in the main unit. Both Centigrade (°C) and Fahrenheit (°F) can be read.

Reading resolution is 0.2°C/0.72°F of Type K and 0.3°C/0.54°F of Type J.

All data transfers and parameter settings are adjusted via modbus. LCM-4TC consumes 35mA current from LX3V main unit or active extension unit's 5V power supply slot. Thermocouples with the following specifications can be used: Type K, Type J.

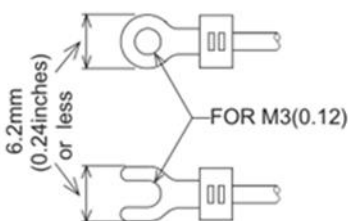
2. Dimensions



- | | |
|--|---------------------------------|
| ① COM: Communication & acquisition board comm. Indicator | ⑤ 485 comm. terminal |
| ERR: Channel calibration indicator | ⑥ DC24V power supply |
| ② 24V: 24V indicator | ⑦ Name of extension module |
| ③ TC: Four channel input/output indicators | ⑧ DIN rail mounting slot |
| ④ LINK: RS485 comm. indicator | ⑨ DIN rail hook |
| | ⑩ Mounting holes ($\phi 4.5$) |

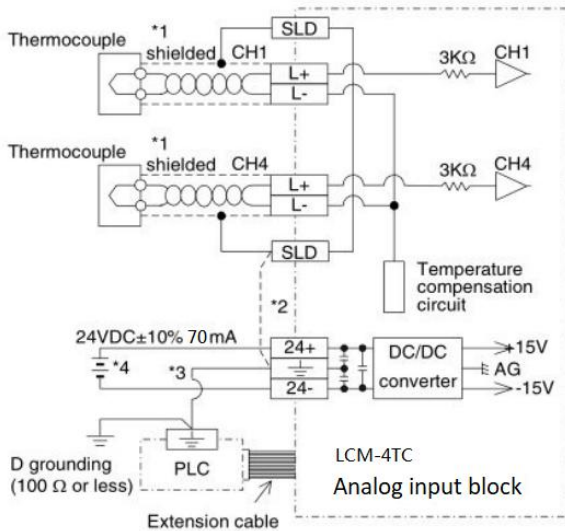
| Name | Description | Indicator state | State |
|----------------|---|-----------------|--|
| LINK indicator | RS485 comm. indicator | Blink | Normal |
| | | OFF | Comm.is abnormal or failed |
| | | ON | Software is running abnormally or hardware failure |
| COM indicator | Communication & acquisition board comm. indicator | Blink | Normal |
| | | OFF | Data exchanging is abnormal or failed or stop |
| | | ON | Software is running abnormally or hardware failure |
| TC indicator | Input/output indicators | Blink | Analog input is over range |
| | | OFF | Analog input is in range |
| | | ON | Channel is closed |
| ERR indicator | Channel calibration indicator | OFF | Calibrate successfully |
| | | ON | Calibration failed or not calibrated |

2.1 Terminal



- Be sure to use the terminals that fits the dimensional requirements.
- Apply 0.5 to 0.8 N.m (5 to 8 kgf.cm) torque to tighten the terminals
- Other terminals should be empty but only wiring terminals mention in this manual.

3. Wiring



- 1) The compensating cables that can be used for connecting with the thermocouple are listed as below:

Type K: KX-G, KX-GS, KX-H, KX-HS, WX-G, WX-H, VX-G

Type J: JX-G, JX-H

For every 1Ω of line resistance, the compensating cable will indicate a temperature 0.12°C higher than actual.

Check the line resistance before using.

Long compensating cables are more prone to noise interference.

Therefore a short (less than 100m) compensating cable is recommended.

Unused channels should have a wire link connected between the + and – terminals to prevent an errors being detected on that channel.

- 2) If there is excessive electrical noise, connect the FG terminal to the ground terminal on the unit.
- 3) Connect the ground terminals of the LX3V-4TC module and the PLC.
- 4) The built-in 24V DC supply of the PLC can be used as the power supply.

4. Installation

4.1 Environmental specification

| Item | Specification |
|------------------------------|--|
| Environmental specifications | Same as LX3V plc unit |
| Insulation withstand voltage | 500V AC, 1min (between all terminals and ground) |

4.2 Power supply specification

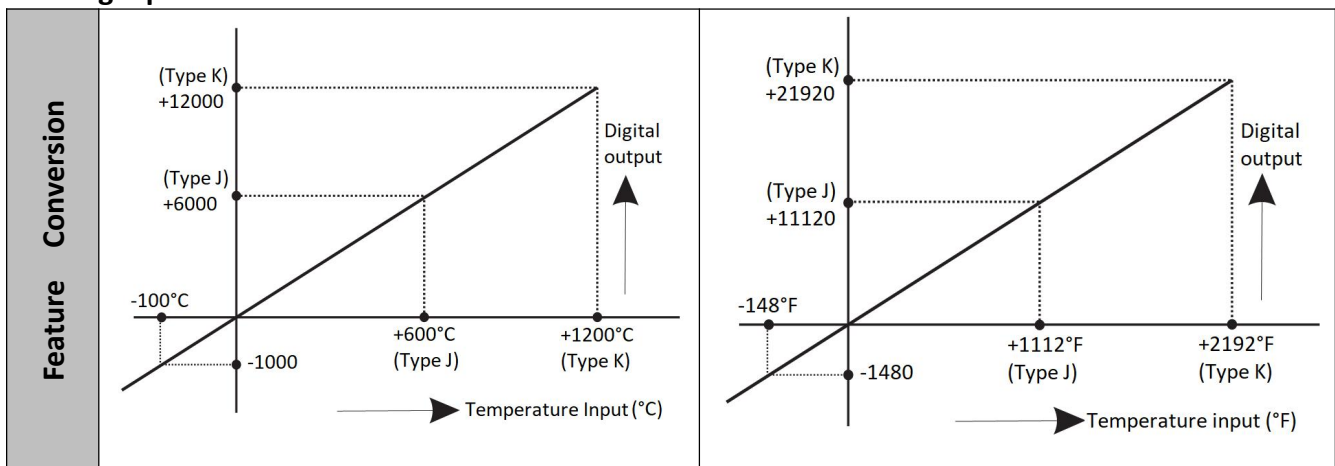
| Item | Description |
|------------------|--|
| Analog circuits | 24V DC \pm 10%, 70mA |
| Digital circuits | 5V DC, 35mA(Main unit internal power supply) |

4.3 Performance indicator

| Item | Centigrade | | Fahrenheit | |
|-------------------------|--|------------------|------------|-------------------|
| | Both °C and °F readings are available by reading the appropriate buffer memory area. | | | |
| Analog input signal | Thermocouple: Type K or J (either can be used for each channel), 4 channels. | | | |
| Rated temperature range | Type K | -100°C to 1200°C | Type K | -148°F to +2192°F |
| | Type J | -100°C to 600°C | Type J | -148°F to +1112°F |
| Digital output | Type K | -1000 to 12000 | Type K | -1480 to 21920 |
| | Type J | -1000 to 6000 | Type J | -1480 to 11120 |
| | 12-bit conversion ,save as complement of 2 in 16 bits | | | |
| Resolution | Type K | 0.4°C | Type K | 0.72°F |
| | Type J | 0.3°C | Type J | 0.54°F |
| Overall accuracy | ±5% full scale + 1°C Freezing point of pure water 0°C / 32°F | | | |
| Conversion speed | (240ms ± 2%) × 4 channels (unused channels are not converted) | | | |

Note: Grounded thermocouples are not suitable for this module.

Analog input



Other

| Item | Description |
|---------------------|---|
| Isolation | Photo-coupler isolation between analog and digital circuits. DC/DC converter is used to isolate LCM-4TC and the LX3V main unit. No isolation between analog channels. |
| Occupied I/O points | 8 points taken from the LX3V expansion bus (can be either inputs or outputs) |

4.4 Buffer memory (BFM)

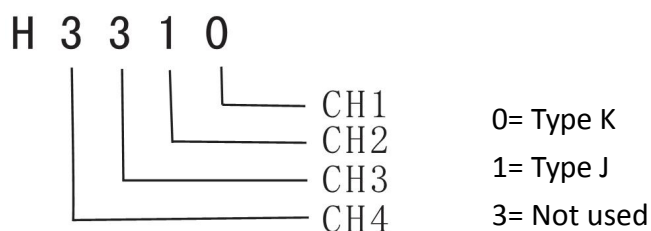
| BFM | Description |
|----------|---|
| *#0 | Thermocouple Type K or J selection mode. Default value: H0000 |
| *#1→ #4 | Number of samples for each channel (1 to 4,096) Default = 8 |
| #5→ #8 | CH1 to CH4 Averaged temperature in 0.1°C units |
| #9→ #12 | CH1 to CH4 Present temperature in 0.1°C units |
| #13→ #16 | CH1 to CH4 Averaged temperature in 0.1°F units |
| #17→ #20 | CH1 to CH4 Present temperature in 0.1°F units |
| #21→ #27 | Reserved |
| #28 | Digital range error latch |
| #29 | Error status |
| #30 | Identification code K6030 |
| #31 | Software version |

- The LCM-4TC module communicates with the PLC via buffer memories.
- BFMs #21 to #27 and #31 are reserved. All non-reserved BFMs can be read by the PLC using the FROM instruction.
- BFMs (buffer memories) marked with an "*" means it can be written with the modbus function code 0x06 or 0x10.

1) Buffer Memory BFM #0: Thermocouple Type K or J selection mode

BFM #0 is used to select Type K or J thermocouples for each channel. Each digit of a 4 digit hexadecimal number corresponds to one channel, the least significant digit corresponds to channel 1.

Example



- A/D conversion time is 240ms per channel. When "3" (unused) is set for a channel, A/D conversion is not executed for that channel, therefore, the total conversion time is decreased. In the above example, the conversion time is as follows:

$$\underline{240\text{ms (conversion time per channel)} \times 2\text{channels (number of channels used)} = 480\text{ms (total conversion time)}}$$

2) Buffer Memory BFMs #1 to #4: Number of samples for each channel

When number of samples for each channel (BFMs #1 to #4) is done, the averaged data is stored

in BFM#s #5 to #8 (°C) and #13 to #16 (°F). The range of BFM#s #1 to #4 is 1~256. If a value outside of this range is entered, the default value 8 will be used.

3) Buffer Memory BFM#s #9 to #12 and #17 to #20: Present temperature

These BFM#s store the present value of the input data. This value is stored in units of 0.1°C or 0.1°F, but the resolution is only 0.4°C or 0.72°F for Type K and 0.3°C or 0.54°F for Type J.

4.5 States information

1) Buffer memory BFM#28: Digital range error latch

BFM #29 b10 (digital range error) is used to judge whether the measured temperature is within the unit's range or not.

BFM #28 latches the error status of each channel and can be used to check for thermocouple disconnection.

| b15 or b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|-----------|------|-----|------|-----|------|-----|------|-----|
| Not used | High | Low | High | Low | High | Low | High | Low |
| | CH4 | | CH3 | | CH2 | | CH1 | |

Low: Turn ON when temperature goes below the lower limit.

High: Turn ON when temperature goes above the upper limit, or when a thermocouple is disconnected.

When an error occurs, the temperature data is latched. If the measured value returns to valid range then the temperature will show as usual. (Note: The error remains latched in (BFM #28))

An error can be cleared by writing K0 to BFM #28 using the TO instruction or turning off the power.

2) Buffer memory BFM#29: Error states

| BFM#29 Bit device | ON | OFF |
|-----------------------|--|--|
| b0: Error | When any of b1 to b3 is ON, A/D conversion is stopped for the error channel | No error |
| b1: Reserved | Reserved | Reserved |
| b2: Power error | 24V DC power supply failure | Power supply is normal |
| b3: Hardware error | A/D converter or other hardware failure | Hardware is normal |
| b4 to b9: Reserved | Reserved | Reserved |
| b10: Data range error | Digital output/analog input value exceeds the range. | Digital output value is normal |
| b11: Averaging error | Selected number of averaged results exceeds the available range. See BFM#1 to #4 | Averaging is normal (between 1 to 256) |
| b12 to b15: Reserved | Reserved | Reserved |

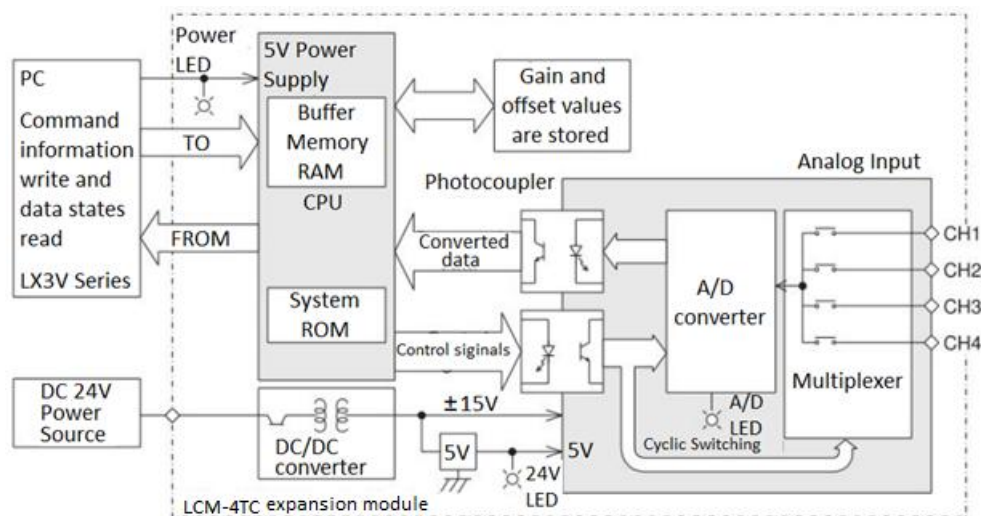
3) identification Code Buffer Memory BFM #30

The identification code or ID number for module is read from buffer memory BFM #30 using the FROM command.

This identification code for the LCM-4TC unit is K6030.

The PLC can use this identification code to identify the expansion module before communicate with the expansion module.

5. System block diagram



6. MODBUS settings

6.1 Com port communication configuration

| Com port comm. configuration | |
|------------------------------|------------------------------------|
| Station No. | 1~32 (Adjust by DIP switch) |
| Baud rate | 9600~115200 (Adjust by DIP switch) |
| Stop bit | 1 |
| Data bit | 8 |
| parity | even |

6.2 Communication

The communication protocol is Modbus, support function codes 03 (read holding register), 06 (write single register), and 16 (write multiple registers).

1) 0x03 function code description

Request (send from master)

| | | |
|---------------|---------|---------------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 1 byte | 0x03 |
| Start address | 2 bytes | 0x0000 to 0xFFFF |
| Register No. | 2 bytes | 1 to 125 |
| CRC | 2 bytes | CRC of all the above data |

Respond (reply from slave)

| | | |
|----------------|-----------|---------------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 1 byte | 0x03 |
| Byte number | 1 byte | 2*N |
| Register value | N*2 bytes | |
| CRC | 2 bytes | CRC of all the above data |

Note: N is the number of register.

Error (reply from slave)

| | | |
|----------------|---------|--|
| Slave address | 1 byte | Slave station No. |
| Error code | 1 byte | 0x83 |
| Exception code | 1 byte | 01 (not support this function code) 02 (Address over range) |
| CRC | 2 bytes | CRC of all the above data |

Example: reading the value of the holding register (0x0000-0x0001) from slave (station No. 0x0f)

| Send from master | | Reply from slave | |
|----------------------------|------|-------------------------|------|
| Slave address | 0x0F | Slave address | 0x0F |
| Function code | 0x03 | Function code | 0x03 |
| Holding register high byte | 0x00 | Byte number | 0x04 |
| Holding register low byte | 0x00 | High byte of register 0 | 0x00 |
| High byte of read No. | 0x00 | low byte of register 0 | 0x0F |
| Low byte of read No. | 0x02 | High byte of register 1 | 0x00 |
| CRC low byte | 0xC5 | low byte of register 1 | 0x01 |
| CRC high byte | 0x25 | CRC low byte | 0xE4 |
| | | CRC high byte | 0x30 |

2) 0x06 function code description

Request (send from master)

| | | |
|----------------|---------|---------------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 1 byte | 0x06 |
| Start address | 2 bytes | 0x0000 to 0xFFFF |
| Register value | 2 bytes | 0x0000 to 0xFFFF |
| CRC | 2 bytes | CRC of all the above data |

Reply (reply from slave)

| | | |
|------------------|---------|---------------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 1 byte | 0x06 |
| Register address | 2 bytes | 0x0000 to 0xFFFF |
| Register value | 2 bytes | 0x0000 to 0xFFFF |
| CRC | 2 bytes | CRC of all the above data |

Error (reply from slave)

| | | |
|----------------|---------|--|
| Slave address | 1 byte | Slave station No. |
| Error code | 1 byte | 0x86 |
| Exception code | 1 byte | 01 (not support this function code) 02 (Address over range) |
| CRC | 2 bytes | CRC of all the above data |

Example: writing 0x001 to address 0x00A from slave(station No. 0x0f)

| Send from master | | Reply from slave | |
|-----------------------------|------|-----------------------------|------|
| Slave address | 0x0F | Slave address | 0x0F |
| Function code | 0x06 | Function code | 0x06 |
| Holding register high byte | 0x00 | Register High byte | 0x00 |
| Holding register low byte | 0x0A | Register low byte | 0x0A |
| High byte of register value | 0x00 | High byte of register value | 0x00 |
| Low byte of register value | 0x01 | low byte of register value | 0x01 |
| CRC low byte | 0x69 | CRC low byte | 0x69 |
| CRC high byte | 0x26 | CRC high byte | 0x26 |

3) 0x10 Function code description

Request (send from master)

| | | |
|---------------|---------|-------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 2 bytes | 0x10 |

| | | |
|----------------|-----------|---------------------------|
| Start address | 2 bytes | 0x0000 to 0xFFFF |
| Register No. | 2 bytes | 0x0001 to 0x0078 |
| Byte No. | 1 byte | 2*N |
| Register value | N*2 bytes | VALUE |
| CRC | 2 bytes | CRC of all the above data |

Reply (reply from slave)

| | | |
|------------------|---------|---------------------------|
| Slave address | 1 byte | Slave station No. |
| Function code | 1 byte | 0x01 |
| Starting address | 2 bytes | 0x0000 to 0xFFFF |
| Register No. | 2 bytes | 1 to 123 |
| CRC | 2 bytes | CRC of all the above data |

Error (reply from slave)

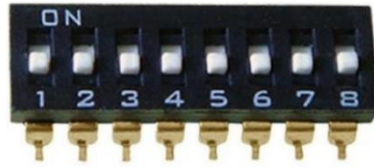
| | | |
|----------------|---------|--|
| Slave address | 1 byte | Slave station No. |
| Error code | 1 byte | 0x90 |
| Exception code | 1 byte | 01 (not support this function code) 02 (Address over range) |
| CRC | 2 bytes | CRC of all the above data |

Example: writing 0x001 to address 0x00A from slave (station No. 0x0f)

| Send from master | | Reply from slave | |
|---------------------------|------|---------------------------|------|
| Slave address | 0x0F | Slave address | 0x0F |
| Function code | 0x06 | Function code | 0x06 |
| Start address High byte | 0x00 | Start address High byte | 0x00 |
| Start address low byte | 0x0A | Start address low byte | 0x0A |
| High byte of register No. | 0x00 | High byte of register No. | 0x00 |
| low byte of register | 0x02 | low byte of register | 0x02 |
| Byte No. | 0x04 | CRC low byte | 0x29 |
| High byte of register 0 | 0x00 | CRC high byte | 0x27 |
| low byte of register 0 | 0x01 | | |
| High byte of register 1 | 0x00 | | |
| low byte of register 1 | 0x02 | | |
| CRC Low byte | 0x76 | | |
| CRC Low byte | 0xB3 | | |

6.3 Introduction of DIP switch

1) DIP switch introduction



| 8-6 | Baud rate |
|-----|-----------|
| 000 | 115200 |
| 001 | 57600 |
| 010 | 38400 |
| 011 | 19200 |
| 100 | 9600 |
| 101 | Reserved |
| 110 | Reserved |
| 111 | Reserved |

5-1: Use to select station number

Figure 6- 1 DIP switch

Note:

In practical use, the dial switch is ON (1) downward and OFF (0) upward. As shown in the figure, the status of the DIP switch is downward, all are ON.

2) DIP switch and station setting

In practical use, the # 1 to # 5 of the DIP switch is used for the selection of the module station number, and the relationship between the station number and the 1 # 5 dial number switch is shown in the following table:

| #1 DIP switch | #2 DIP switch | #3 DIP switch | #4 DIP switch | #5 DIP switch | Module station |
|---------------|---------------|---------------|---------------|---------------|----------------|
| 0 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | 0 | 0 | 0 | 2 |
| 0 | 1 | 0 | 0 | 0 | 3 |
| 1 | 1 | 0 | 0 | 0 | 4 |
| 0 | 0 | 1 | 0 | 0 | 5 |
| 1 | 0 | 1 | 0 | 0 | 6 |
| 0 | 1 | 1 | 0 | 0 | 7 |
| 1 | 1 | 1 | 0 | 0 | 8 |
| 0 | 0 | 0 | 1 | 0 | 9 |
| 1 | 0 | 0 | 1 | 0 | 10 |
| 0 | 1 | 0 | 1 | 0 | 11 |
| 1 | 1 | 0 | 1 | 0 | 12 |
| 0 | 0 | 1 | 1 | 0 | 13 |
| 1 | 0 | 1 | 1 | 0 | 14 |

| | | | | | |
|---|---|---|---|---|----|
| 0 | 1 | 1 | 1 | 0 | 15 |
| 1 | 1 | 1 | 1 | 0 | 16 |
| 0 | 0 | 0 | 0 | 1 | 17 |
| 1 | 0 | 0 | 0 | 1 | 18 |
| 0 | 1 | 0 | 0 | 1 | 19 |
| 1 | 1 | 0 | 0 | 1 | 20 |
| 0 | 0 | 1 | 0 | 1 | 21 |
| 1 | 0 | 1 | 0 | 1 | 22 |
| 0 | 1 | 1 | 0 | 1 | 23 |
| 1 | 1 | 1 | 0 | 1 | 24 |
| 0 | 0 | 0 | 1 | 1 | 25 |
| 1 | 0 | 0 | 1 | 1 | 25 |
| 0 | 1 | 0 | 1 | 1 | 27 |
| 1 | 1 | 0 | 1 | 1 | 28 |
| 0 | 0 | 1 | 1 | 1 | 29 |
| 1 | 0 | 1 | 1 | 1 | 30 |
| 0 | 1 | 1 | 1 | 1 | 31 |
| 1 | 1 | 1 | 1 | 1 | 32 |

3) DIP switch and baud rate setting

In practical use, the #6 to #8 of the DIP switch are used for the selection of the baud rate, and the relationship between the baud rate and #6-# 8 DIP switch is shown in the following table:

| #6 DIP switch | #7 DIP switch | #8 DIP switch | Module baud rate |
|---------------|---------------|---------------|--|
| 0 | 0 | 0 | 115200 |
| 1 | 0 | 0 | 57600 |
| 0 | 1 | 0 | 38400 |
| 1 | 1 | 0 | 19200 |
| 0 | 0 | 1 | 9600 |
| 1 | 0 | 1 | Reserved for later expansion (Default: 115200) |
| 0 | 1 | 1 | Reserved for later expansion (Default: 115200) |
| 1 | 1 | 1 | Reserved for later expansion (Default: 115200) |

6.4 Note

LCM-4TC and LX3V-4TC differentiate in communication method, but the register functions are the same.

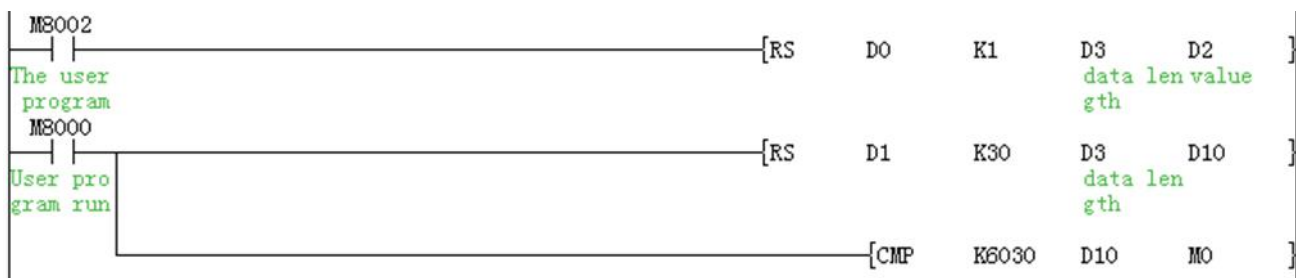
| Module | Max. accessible address (BFM address) |
|--------|---------------------------------------|
| 4TC | 31 |

7. Exmample

The following example set the station number as 2, baud rate as 115200 via the DIP switch. Type K thermocouple is used for CH1, Type J thermocouple is used for CH2, CH3 and CH4 are not used. The average number is 4. The average values (°C) of the input channels CH1 to CH4 are stored in the data registers D20 to D23 respectively.



Above demo means plc com2 is Modbus master, communication parameter is 115200, 1, 8, even.

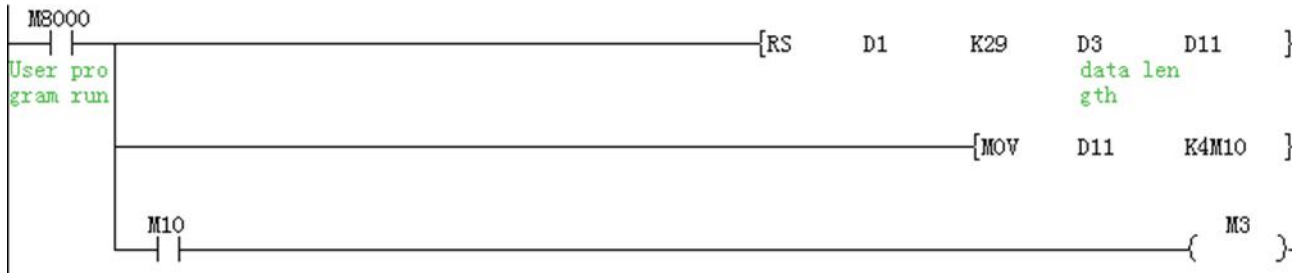


Thermocouple type is defined by BFM0, here is H3310.

CH4: closed (3) , CH3: closed(3), CH2: type J(1), CH1: type K(0)

D10 reads from the BFM30, when D10=K6030, then m1=ON. It is not compulsory to check BFM30 in the program.

If the module with checkpoint number 2 is LCM-4TC in the initialization step, that is, if its unit identification code is K6030 (BFM#30). This step is optional, but it provides a way for software to check that the system is configured correctly.



BFM29 (K4M10) assign value to m25~m10. When there is an error, m10=1. M10 is the bit0 of BFM 29.

This step provides optional monitoring of the error buffer memory (#29) of LCM-4TC. If there is an error in LCM-4TC, bit0 of BFM#29 will be set to ON. This can be read by this program step and output as a bit device in an LX3V programmable controller (M3 in this case). Additional error devices can be output in the same way, such as b10 for BFM#29. (see below)



M3 is the b0 of BFM#29, M4 is the b10 of BFM#29.

BFM#5 to BFM#8 is stored in D0 to D3 in the unit of °C as an average temperature.

The last line is for reading the average temperature and stored in D30~D33.

8. Diagnosis

8.1 Preliminary examination

- 1) Check if the input/output wiring and/or extension cable are connected to the LCM-4TC module.
- 2) Check if the number of special functions modules exceeds 16, and the total number of system I/O points cannot exceed 256 points.
- 3) Ensure that the correct operating range is selected in the program.
- 4) Check that there is no power overload in the 5V or 24V power supply.
- 5) The LX3V main unit is at the RUN state.

8.2 check error

If LCM-4TC does not work properly, please check the following items.

- Check the status of the power LED
ON: the extension cable is properly connected
Otherwise: Check the connection of the extension cable.
- Check external wiring
- Check the status of the "24V" LED (upper right corner of the LCM-4TC)
ON: The LCM-4TC is normal and the 24VDC power supply is normal.
Otherwise: The 24V DC power supply may be faulty. If the power supply is normal, the LCM-4LTC is faulty.
- Check the status of the "A/D" LED (upper right corner of LCM-4TC)
Lit: A/D conversion works normally.
Otherwise: Check buffer memory #29 (error status). If any of the bits (b2 and b3) are in the ON state, which is why the A/D indicator is off.

9. EMC

- Electromagnetic compatibility or EMC must be considered before using the LCM-4TC.
- WECON recommends that the thermocouple sensors used, should be fitted with a form of shield or screening as protection against EMC noise.
- If some form of cable protection is used, the "Shield" must be terminated at the terminals as shown in chapter 3.

-
- Because of the delicate nature of all analog signals, failure to take good EMC precautions could lead to EMC noise induced errors; up to $\pm 10\%$ of actual values. This is an absolute worst case figure, users who do take good precautions can expect operation within normal tolerances. EMC considerations should include selection of good quality cables, good routing of those cables away from potential noise sources.
 - Additionally it is recommended that signal averaging is used as this will reduce the effects of random noise “spikes”