WECON
LX3V-4PT
MODULES

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LX3V-4PT Extension module

1. Introduction

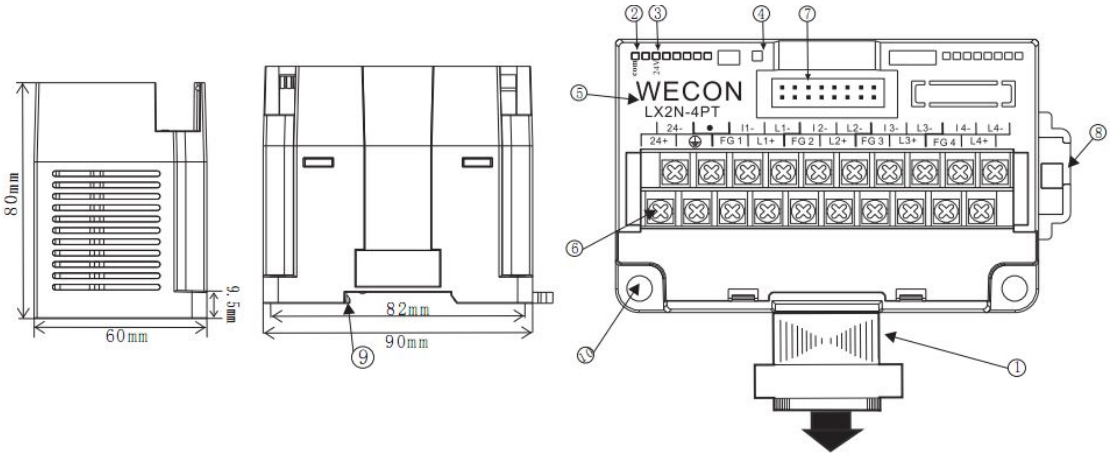
The LX3V-4PT analog block amplifies the input from four platinum temperature sensors (PT 100, 3 wire, 100 Ω) and converts the data into 12 bit reading's stored in the Main Processing Unit (MPU). Both Centigrade (°C) and Fahrenheit (°F) can be read. Reading resolution is 0.2°C to 0.3°C / 0.36°F to 0.54°F.

The LX3V-4PT occupies 8 points of I/O on the LX3V expansion bus. The 8 points can be allocated from either in-puts or outputs. The LX3V-4PT draws 30mA from the 5V rail of the MPU or powered extension unit.

LX3V-4PT consume 5V voltage from LX3V main unit or active extension unit,90mA current of power supply.

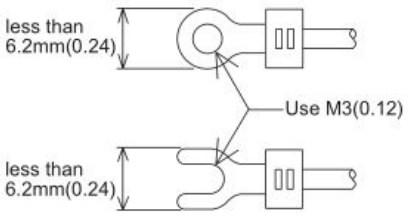
2. External dimensions

Weight:Approx 0.3kg (0.661bs) Dimensions:mm



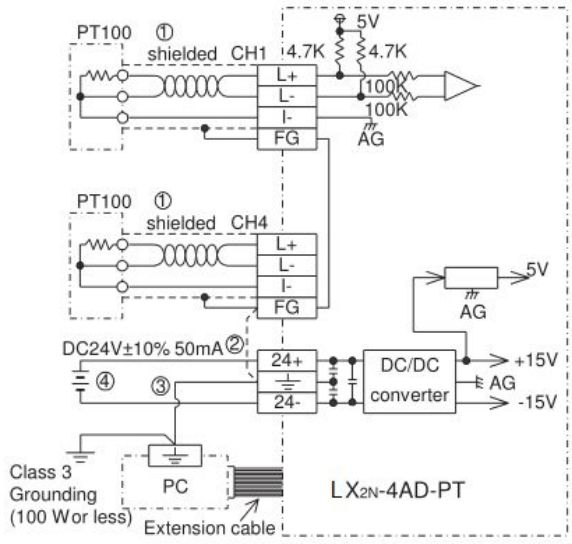
① Extension cable and connector
② Com LED:Light when communicating
③ Power LED:Light when connect to 24V
④ State LED:Light when normal condition
⑤ Module name
⑥ Analog signal output terminal
⑦ Extension module interface
⑧ DIN rail mounting slot
⑨ DIN rail hook
⑩ Mounting holes(φ4.5)

Using crimp terminations



- Use crimp terminations of the type indicated on the left.
- Secure the termination using a tightening torque of between 5 and 8 kg·cm.
- Wire only to the module terminals discussed in this manual. Leave all others vacant.

3.Terminal Layouts



① The cable of the PT 100 sensor or a twisted shielded cable should be used for the analog input cable. This analog input cable should be wired separately from power lines or any other lines which may induce noise. The three wire method improves the accuracy of the sensors by compensating voltage drops.

② If there is electrical noise, connect the frame ground terminal (FG) with the ground terminal.

③ Connect the ground terminal on the LX2N-4AD-PT unit with the grounded terminal on the base unit. Use class 3 grounding on the base unit, if grounding is possible.

④ Either an external or the 24V built-in supply in the programmable controller may be used.

For additional data regarding EMC considerations please see section 7.0.

4.Installation notes and usage

4.1 Environmental specification

Item	Specification
Environmental specifications (excluding following)	Same as those for the LX3V base unit
Dielectric withstand voltage	500V AC, 1min (between all terminals and ground)

4.2 Power supply specification

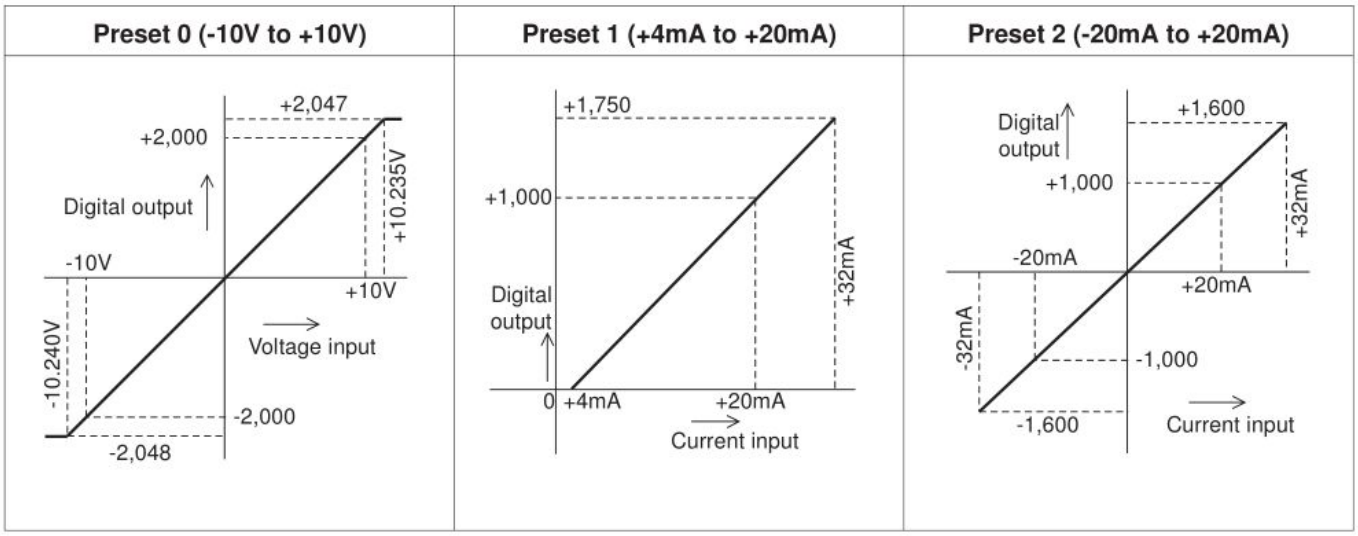
Item	Description
Analog circuits	±24V DC±10%,55mA
Digital circuits	5V DC,90mA(internal power supply from base unit)

4.3 Performance specification

Analog inputs

Item	Centigrade	Fahrenheit
	Both °C and °F readings are available by reading the appropriate buffer memory area.	
Analog input signal	Platinum temperature PT 100 sensors (100 Ω), 3-wire, 4-channel (CH1, CH2,CH3, CH4), 3850 PPM/°C	
Current to sensor	1 mA. sensor : 100 Ω PT 100	
Compensated range	100℃ to 600℃	-148℉ to +1112℉
Digital output	-1000 to 6000	-1480 to 11120
	12-bit conversion 11 data bits +1 sign bit	
Minimum resolvable temp.	0.2℃ to 0.3℃	0.36℉ to 0.54℉
Overall accuracy	±1% full scale (compensated range) -see section 7.0 for special EMC considerations	
Conversion speed	4Channel 15ms	

Analog inputs continued……



NOTE: Preset ranges are selected by an appropriate setting in buffer memory of the analog block.Current/Voltage input selection must match the correct input terminal connections.

Miscellaneous

Item	Description
Isolation	Photo-coupler isolation between analog and digital circuits. DC/DC converter isolation of power from LX2NMPU. No isolation between analog channels.
Total points	8 points taken from the LX2N expansion bus (can be either inputs or outputs)

4.4 Buffer memory assignment

BFM	Content
*#1→#4	CH1 to CH4 Averaged temperature reading to be averaged (1 to 4,096) Default = 8
*#5→#8	CH1 to CH4 Averaged temperature in 0.1°C units
*#9→#12	CH1 to CH4 Present temperature in 0.1°C units
*#13→#16	CH1 to CH4 Averaged temperature in 0.1°F units
*#17→#20	CH1 to CH4 Present temperature in 0.1°F units
*#21→#27	Reserved
*#28	Digital range error latch
#29	Error status
#30	Identification code K2040
#31	Software version

(1) The number of samples to be averaged are assigned in BFMs #1 to #4. Only the range 1 to 4096 is valid. Values outside this range are ignored. The default value of 8 is used.
(2) A number of recently converted readings are averaged to give a smoother read out. The averaged data is stored in BFMs #5 to #8 and #13 to #16.
(3) BFMs #9 to #12 and #17 to #20 store the current value of the input data. This value is in units of 0.1°C or 0.1°F, but the resolution is only 0.2°C to 0.3°C or 0.36°F to 0.54°F.

4.5 Status information

(1) Buffer memory BFM #28:Digital range error latch

BFM #29 b10(digital range error) is used to judge whether the measured temperature is within the unit's range or not.

BFM #28 latches the error status of each channel and can be used to check for thermocouple

disconnection.

b15 or b8	b7	b6	b5	b4	b3	b2	b1	b0
Not used	High	Low	High	Low	High	Low	High	Low
	CH4		CH3		CH2		CH1	

Low: Latches ON when temperature measurement data goes below the lowest temperature measurement limit.

High: Turns ON when temperature measurement data goes above the highest temperature measurement limit, or when a thermocouple is disconnected.

When an error occurs the temperature data before the error is latched. If the measured value returns to within valid limits the temperature data returns to normal operation. (Note: The error remains latched in (BFM #28))

An error can be cleared by writing K0 to BFM #28 using the TO instruction or turning off the power.

(2) Buffer Memory BFM #29: Error status

BFM#29 Bit device	ON	OFF
b0:Error	When any of b1 to b3 is ON A/D conversion is stopped for the error channel	No error
b1:Reserved	Reserved	Reserved
b2:Power source	24VDC power supply failure	Power supply normal
b3:Hardware error	A/D converter or other hardware failure	Hardware Normal
b4 to b9:Reserved	Reserved	Reserved
b10: Digital range error	Digital output/analog input value is outside the specified range.	Digital output value is normal.
b11:Averaging error	Selected number of averaged results is outside the available range.see BFM #1 to #4	Averaging is normal. (between 1 to 4096)
b12 to b15:Reserved	Reserved	Reserved

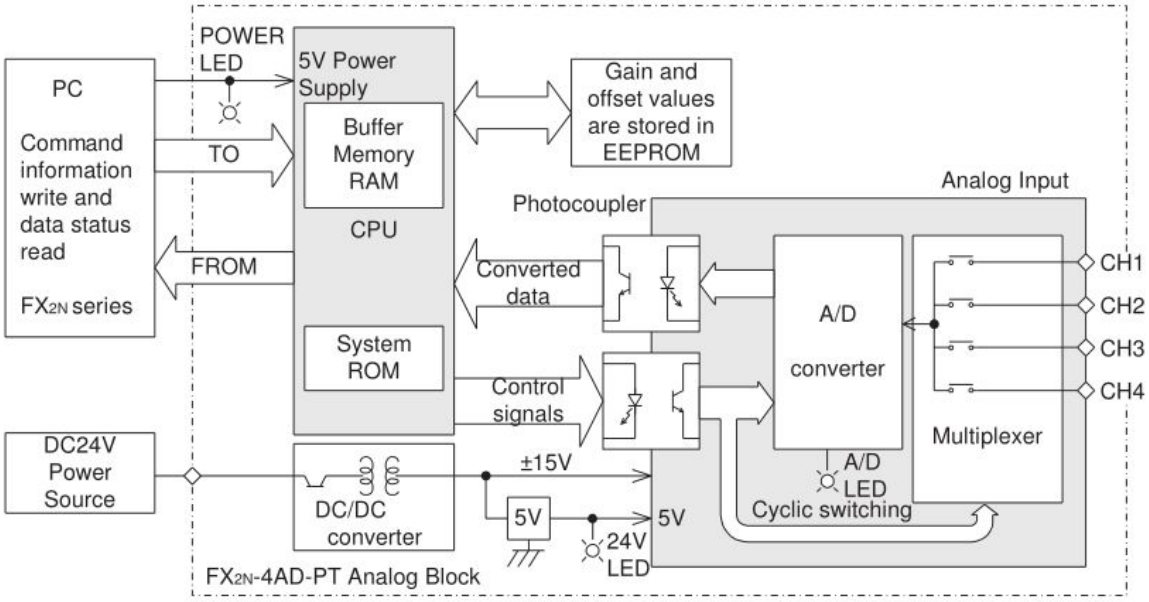
(3) Identification Code Buffer Memory BFM #30

The identification code or ID number for a Special Block is read from buffer memory BFM #30 using the FROM command.

This number for the LX2N-4AD-PT unit is K2040.

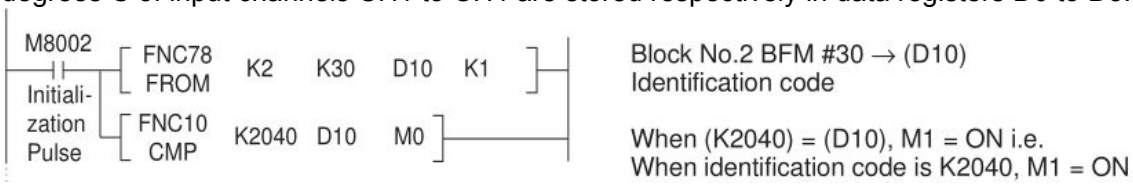
The programmable controller can use this facility in its program to identify the special block before commencing data transfer from and to the special block

5. System block diagram



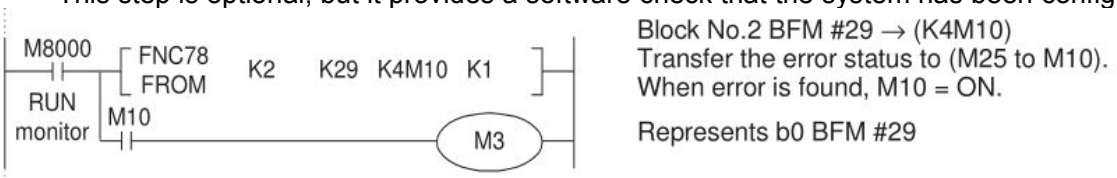
6.Example program

In the program shown below, the LX2N-4AD-PT block occupies the position of special block number 2 (that is the third closest block to the programmable controller). The averaging amount is four. The averaged values in degrees C of input channels CH1 to CH4 are stored respectively in data registers D0 to D3.



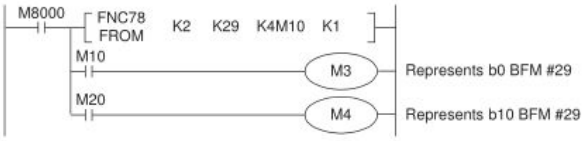
This initial step checks that the special function block placed at position 2 is actually an LX2N-4AD-PT, i.e. its unit identification number is 2040 (BFM #30).

This step is optional, but it provides a software check that the system has been configured correctly.



This step provides optional monitoring of the LX2N-4AD-PT Error Buffer Memory (#29). If there is an Error ont the LX2N-4AD-PT, bit b0 of BFM #29 will be set on.

This can be read by this program step, and output as a bit device in the LX2N programmable controller (M3 in this example). Additional Error devices can be output in a similar manner, i.e. b10 BFM #29. (see below)

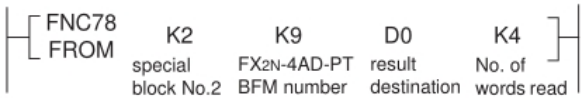


(K4) → (BFM #1 to #4)
Number of samples is changed four on CH1 to CH4.

(BFM #5 to #8) → (D0 to D3)
Transfer the averaged temperature value in °C to the data registers.

This step is the actual reading of the LX2N-4AD-PT input channels. It is essentially the only program step which is needed. The “TO” instruction in this example, sets the input channels, CH1 to CH4, to take the average reading of four samples.

The “FROM” instruction reads the average temperatures (BFM #5 to #8) for input channels CH1 to CH4 of the LX2N-4AD-PT. If direct temperature readings are required BFM #9 to #12 should be read instead, ex.



7.Diagnostics

7.1 Preliminary checks

I. Check whether the input/output wiring and/or extension cables are properly connected on LX2N-4AD-PT analog special function block

II. Check that the LX2N system configuration rules have not been broken, i.e. the number of special function blocks does not exceed 8 and the total system I/O is equal or less than 256, I/O.

III. Ensure that the correct operating range has been selected for the application.

IV. Check that there is no power overload on either the 5V or 24V power sources, remember the loading on an MPU or a powered extension unit varies according to the number of extension blocks or special function blocks connected.

V. Put the Main Processing Unit (MPU) into RUN.

7.2 Error checking

If the LX2N-4AD-PT special function block does not seem to operate normally, check the following items.

- Check the status of the POWER LED.

Lit:The extension cable is properly connected.

Otherwise:Check the connection of the extension cable.

- Check the external wiring.
- Check the status fo the “24V” LED (top right corner of the LX2N-4AD-PT).

Lit:LX2N-4AD-PT is ON, 24V DC power source is ON.

Otherwise:Possible 24VDC power failure, if ON possible LX2N-4AD-PT failure.

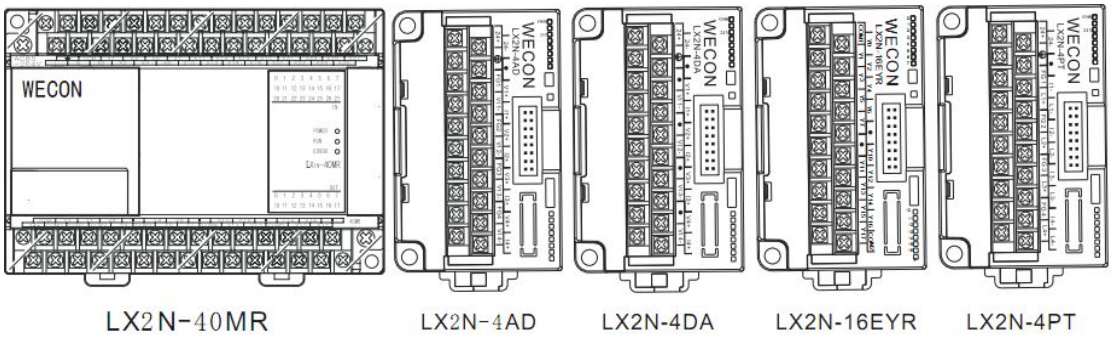
- Check the status fo the “A/D” LED (top right corner of the LX2N-4AD-PT).

Lit:A/D conversion is proceeding normally.

Otherwise :Check buffer memory #29 (error status). If any bits (b0, b2, b3) are ON, then this is why the A/D LED is OFF.

7.3 Checking special function block numbers

Other special units of blocks that use FROM/TO commands, such as analog input blocks, analog output blocks and high-speed counter blocks, can be directly connected to the base unit of the LX2N programmable controller or to the right side of other extension blocks or units. Each special block is consecutively numbered from 0 to 15 beginning from the one closest to the base unit. A maximum of eight special blocks can be connected.



8. EMC Considerations

Electromagnetic compatibility or EMC must be considered before using the LX3V-4PT.

We recommend that the PT100 sensors used, should be fitted with a form of seild or screening as protection against EMC noise.

If some form of cable protection is used, the”Shield” must be terminated at grounding terminals as shown in section 2.0.

Because of the delicate nature of all analog signals, failure to take good EMC precutions could lead to EMC noise induced error: up to ± 10% of actual values. This is an absolute worst case figure, users who do take good precautions can expect operation within normal tolerances,

EMC considerations should include selection of good quality cables, good routing of those cables away from potential noise sources.

Additionally it is recommended that signal averaging is used as this will reduce the effects of random noise”spikes”.